ST0898 Levelling Course in Computation Master in Data Sciences and Analytics

Andrés Sicard-Ramírez

Universidad EAFIT

June 2019

# Introduction

### Textbook

Aho, A. V., Hopcroft, J. E. and Ullman, J. D. [1983] [1985]. Data Structures and Algorithms. Reprinted with corrections. Addison-Wesley.

### Other books

- Brassard, G. and Bratley, P. [1996]. Fundamentals of Algorithmics. Prentice Hall.
- Parberry, I. and Gasarch, W. [1994] [2002]. Problems on Algorithms. 2nd ed. Prentice Hall.

#### Convention

The references to examples, exercises, figures, quotes or theorems correspond to those in the textbook.

### Examination

The exam will be on Tuesday, 2nd July.

### Course Content

- Elementary algorithms
- Analysis of algorithms
- Abstract data types (lists, stacks and queues)

### Preliminaries

Notation and conventions for number sets

$$\mathbb{N} = \{0, 1, 2, \ldots\}$$
$$\mathbb{Z} = \{\ldots, -2, -1, 0, 1, 2, \ldots\}$$
$$\mathbb{Z}^+ = \{1, 2, 3, \ldots\}$$
$$\mathbb{Q} = \{p/q \mid p, q \in \mathbb{Z} \text{ and } q \neq 0\}$$
$$\mathbb{R} = (-\infty, \infty)$$
$$\mathbb{R}^{\geq 0} = [0, \infty)$$
$$\mathbb{R}^+ = (0, \infty)$$

(natural numbers)

(integers)

(positive integers)

(rational numbers)

(real numbers)

(non-negative real numbers)

(positive real numbers)

# Preliminaries

### Convention

All the logarithms are base 2.

### Appendix

See in the appendix:

- Floor and ceiling functions
- Summation properties

# Elementary Algorithms

Question

Can be any problem solved by a program?

### Question

Can be any problem solved by a program?

No!

- Limitations when specifying the problem (no precise specification)
- Computation limitations (theoretical or practical)
- Ethical considerations and regulations

Quote

'Half the battle is knowing what problem to solve.' (p. 1)

### Quote

'Half the battle is knowing what problem to solve.' (p. 1)

Steps when writing a computer program to solve a problem

- Problem formulation and specification
- Design of the solution
- Implementation
- Testing
- Documentation
- Evaluation
- Maintenance

### Quote

'Half the battle is knowing what problem to solve.' (p. 1)

Steps when writing a computer program to solve a problem

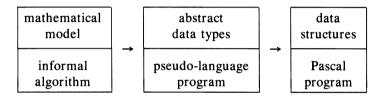
- Problem formulation and specification
- Design of the solution
- Implementation
- Testing
- Documentation
- Evaluation
- Maintenance

### Remark

In software engineering the above steps are part of the software development life cycle.

### The problem solving process

Problem solving stages.\*



\*Figure source: Fig. 1.9.

Definition

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

Question

Are missing the computers on the above definition of algorithm?

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

Question

Are missing the computers on the above definition of algorithm? No!

Definition

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

Question

What is an instruction?

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

Question

What is an instruction?

### Remark

Any informal definition of algorithm necessary will be imprecise (but the above definition is enough for our course).

**Informally**, an **algorithm** is 'a finite sequence of instructions, each of which has a clear meaning and can be performed with a finite amount of effort in a finite length of time.' (p. 2)

Discussion

Is any computer program an algorithm?

Correctness of an algorithm

#### partial correctness := if an answer is returned it will be correct

 $\mathsf{total}\ \mathsf{correctness} := \mathsf{partial}\ \mathsf{correctness} + \mathsf{termination}$ 

# Programming Languages

### Some paradigms of programming

- Imperative/object-oriented: Describe computation in terms of state-transforming operations such as assignment. Programming is done with statements.
- Logic: Predicate calculus as a programming language. Programming is done with sentences.
- Functional: Describe computation in terms of (mathematical) functions. Programming is done with expressions.

### Examples

$$\label{eq:linear} Imperative/OO \begin{cases} C \\ C++ \\ JAVA \\ PYTHON \end{cases} \mbox{Logic} \begin{cases} CLP(R) \\ PROLOG \\ PROLOG \end{cases} \mbox{Functional} \begin{cases} ERLANG \\ HASKELL \\ ML \\ \end{cases}$$

# Programming Languages

Discussion

Does the algorithm for solving a problem depend of the programming language used for implementing it?

We shall write algorithms using pseudo-code.

#### Example

See pseudo-code entry on Wikipedia.\*

<sup>\*</sup>https://en.wikipedia.org/wiki/Pseudocode.

### Conventions

Based on the conventions used in [Cormen, Leiserson, Rivest and Stein 2009, pp. 20-22]:

- Indentation indicates block (e.g. for loop, while loop, if-else statement) structure instead of conventional indicators such as begin and end statements.
- Assignation is denoted by the symbol ':='.
- Basic data types (e.g. integers, reals, booleans and characters) parameters to a procedure are passed by value.
- Compound data types (e.g. arrays) and abstract data types (e.g. lists, stacks and queues) parameters to a procedure are passed by reference.
- The symbols ' $/\!\!/$ ' and ' $\triangleright$ ' denote a commentary.

### Example

Pseudo-code for calculating the factorial of a number (recursive version).

```
Factorial \mathbf{R}(n:\mathbb{N})
```

- 1 if  $n \leq 1$
- 2 **return** 1
- 3 **else**
- 4 return n \* FACTORIALR(n-1)

### Example

Pseudo-code for calculating the factorial of a number (iterative version).

FactorialI $(n:\mathbb{N})$ 

- 1  $fac: \mathbb{Z}^+$
- 2 fac := 1
- 3 for i := 1 to n
- 4 fac := fac \* i
- 5 return fac

### Example

Pseudo-code for calculating the factorial of a number (iterative version).

FactorialI $(n:\mathbb{N})$ 

- 1  $fac: \mathbb{Z}^+$
- 2 fac := 1
- 3 for i := 1 to n
- 4 fac := fac \* i
- 5 return fac

### Remark

Recursive algorithms versus iterative algorithms.

#### Exercise

Assume the parameter n in the function below is a positive power of 2, i.e.  $n = 2, 4, 8, 16, \ldots$ . Give the formula that expresses the value of the variable *count* in terms of the value of n when the function terminates (Exercise 1.17).

 $\operatorname{MISTERY}(n:\mathbb{N})$ 

- 1  $count, x : \mathbb{N}$
- 2 count := 0
- 3 x := 2
- 4 while x < n
- $5 \qquad x := 2 * x$
- $6 \qquad count := count + 1$
- 7 return count

#### Exercise

Which is the value returned by the MYSTERY function? Hint: Keep y fixed. From [Parberry and Gasarch 2002, Exercise 257].

```
MYSTERY(y : \mathbb{R}, z : \mathbb{N})
x : \mathbb{R}
x := 1
while z > 0
if z is odd
x := x * y
z := \lfloor z/2 \rfloor
y := y^2
return x
```

### Example

Brassard and Bratley [1996] describe an algorithm for multiplying two positive integers which does not use any multiplication tables. The algorithm is called multiplication *a la russe*.<sup>\*</sup>

```
RUSSE(m: \mathbb{Z}^+, n: \mathbb{Z}^+)
    result : \mathbb{N}
    result := 0
2
3
    repeat
         if m is odd
4
5
               result := result + n
6
         m := |m/2|
         n := n + n
8
    until m == 0
    return result
9
```

<sup>\*</sup>In Brassard and Bratley [1996], the condition in Line 8 is m == 1, which is wrong. Elementary Algorithms

#### Exercise

Test the **RUSSE** algorithm on some inputs.

# Sorting

### Introduction

A sorting algorithm is an algorithm that puts elements of list according to some linear (total) order. Sorting algorithms are fundamental in Computer Science.

# Sorting

Bubble sort (first version)

```
BUBBLESORT(A : \operatorname{Array}[1 \dots n])
    \triangleright Sorts array A into increasing order.
1
2
    for i := 1 to n - 1
3
         for i := n downto i + 1
               if A[j-1] > A[j]
4
5
                    \triangleright Swap A[j-1] and A[j].
                     temp := A[j-1]
6
                     A[j-1] := A[j]
8
                     A[j] := temp
```

# Sorting

### Bubble sort (second version)

Since a procedure swap is very common in sorting algorithms, we rewrite the bubble sort algorithm calling this procedure.

3

4 5

 $SWAP(A : Array, i : \mathbb{N}, j : \mathbb{N})$ 

1  $\triangleright$  Exchanges A[i] and A[j].

$$2 \quad temp := A[i]$$

$$3 \quad A[i] := A[j]$$

4 A[j] := temp

BUBBLESORT $(A : \operatorname{Array}[1 \dots n])$ 

 $1 \triangleright$  Sorts array A into increasing order.

2 for 
$$i := 1$$
 to  $n - 1$ 

for 
$$j := n$$
 downto  $i + 1$   
if  $A[i-1] > A[i]$ 

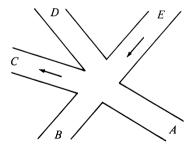
$$\frac{\operatorname{II}[j] \times \operatorname{II}[j]}{\operatorname{SWAP}(A, j-1, j)}$$

#### Problem

To design an optimal traffic light for an intersection of roads (Example 1.1).

### An instance of the problem

In the figure, roads C and E are one-way, the others two way.\*



\*Figure source: Fig. 1.1.

Mathematical model for the problem

We can model the problem via a graph of incompatible turns.

#### Mathematical model for the problem

We can model the problem via a graph of incompatible turns.

#### Some questions about the model

What is a graph? Is the graph directed or undirected in our model? Do we need graphs with or without loops? What about parallel edges?

Notation

Let A be a set. We denote the set of all k-subsets of A by  $[A]^k$ .

#### Notation

Let A be a set. We denote the set of all k-subsets of A by  $[A]^k$ .

### Definition

A graph is an order pair G = (V, E) of disjoint sets such that  $E \subseteq [V]^2$  [Diestel 2017].

### Definition

The vertices and the edges (aristas) of a graph G = (V, E) are the elements of V and E, respectively.

#### Notation

Let A be a set. We denote the set of all k-subsets of A by  $[A]^k$ .

### Definition

A graph is an order pair G = (V, E) of disjoint sets such that  $E \subseteq [V]^2$  [Diestel 2017].

### Definition

The vertices and the edges (aristas) of a graph G = (V, E) are the elements of V and E, respectively.

#### Notation

Let A be a set. The cardinality of A is denoted by |A|.

Some remarks on our definition of graph

• The edges in our graphs are undirected because  $\{v, w\} = \{w, v\}$ .

- The edges in our graphs are undirected because  $\{v, w\} = \{w, v\}$ .
- Since  $\{v, v\} \notin [V]^2$  because  $|\{v, v\}| = |\{v\}| = 1$ , our graphs have no loops.

- The edges in our graphs are undirected because  $\{v, w\} = \{w, v\}$ .
- Since  $\{v,v\} \not\in [V]^2$  because  $|\{v,v\}| = |\{v\}| = 1$ , our graphs have no loops.
- Since the multiplicity of an element in a set is one, our graphs have no parallel edges.

- The edges in our graphs are undirected because  $\{v, w\} = \{w, v\}$ .
- Since  $\{v,v\} \notin [V]^2$  because  $|\{v,v\}| = |\{v\}| = 1$ , our graphs have no loops.
- Since the multiplicity of an element in a set is one, our graphs have no parallel edges.
- A graph with undirected egdes, without loops and without parallel edges is also called a **simple** graph in the literature. E.g. [Bondy and Murty 2008].

- The edges in our graphs are undirected because  $\{v, w\} = \{w, v\}$ .
- Since  $\{v,v\} \notin [V]^2$  because  $|\{v,v\}| = |\{v\}| = 1$ , our graphs have no loops.
- Since the multiplicity of an element in a set is one, our graphs have no parallel edges.
- A graph with undirected egdes, without loops and without parallel edges is also called a **simple** graph in the literature. E.g. [Bondy and Murty 2008].
- The sets V and E must be disjoint for ruling out 'graphs' like  $V=\{a,b,\{a,b\}\}$  and  $E=\{\{a,b\}\}.$

Definition

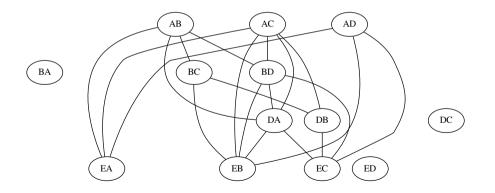
Two vertices x, y of a graph G are **adjacent** or **neighbours**, iff  $\{x, y\}$  is an edge of G.

#### Example

Graph of incompatible turns for the instance of our problem where the vertices represent turns and whose edges represent turns cannot be performed simultaneously.

### Example

Graph of incompatible turns for the instance of our problem where the vertices represent turns and whose edges represent turns cannot be performed simultaneously.



### Definition

Let G = (V, E) be a graph and S be a set whose elements are the available colours.

A colouring of G is a function

$$c: V \to S$$

such that  $c(v) \neq c(w)$  whenever v and w are adjacent.

### Problem equivalence (initial version)

Our problem is equivalent to the problem of colouring the graph of incompatible turns using as few colours as possible.

### Problem equivalence (initial version)

Our problem is equivalent to the problem of colouring the graph of incompatible turns using as few colours as possible.

### Definition

A k-colouring of a graph G is a colouring of G using at most k colours.

### Problem equivalence (initial version)

Our problem is equivalent to the problem of colouring the graph of incompatible turns using as few colours as possible.

### Definition

A k-colouring of a graph G is a colouring of G using at most k colours.

### Definition

Let G be a graph and k be the smallest integer such that G has a k-colouring. This number k is the **chromatic number** of G.

### Problem equivalence (initial version)

Our problem is equivalent to the problem of colouring the graph of incompatible turns using as few colours as possible.

### Definition

A k-colouring of a graph G is a colouring of G using at most k colours.

### Definition

Let G be a graph and k be the smallest integer such that G has a k-colouring. This number k is the **chromatic number** of G.

### Problem equivalence (final version)

Our problem is equivalent to the problem of finding the chromatic number of the graph of incompatible turns.

Some remarks about our new problem

• The problem is a NP-complete problem.

Some remarks about our new problem

- The problem is a NP-complete problem.
- Is a good (no necessarily optimal) solution enough? If so, we could use a heuristic approach.

#### Greedy heuristic

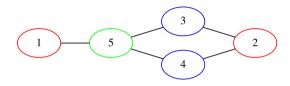
Description from p. 5:

One reasonable heuristic for graph coloring is the following 'greedy' algorithm. Initially we try to color as many vertices as possible with the first color, then as many as possible of the uncolored vertices with the second color, and so on. To color vertices with a new color, we perform the following steps.

- 1. Select some uncoloured vertex and colour it with the new colour.
- 2. Scan the list of uncoloured vertices. For each uncoloured vertex, determine whether it has an edge to any vertex already coloured with the new colour. If there is no such edge, colour the present vertex with the new colour.

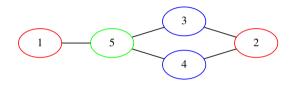
Example (Our greedy heuristic can fail)

Colouring using the heuristic.

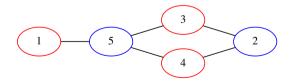


Example (Our greedy heuristic can fail)

Colouring using the heuristic.

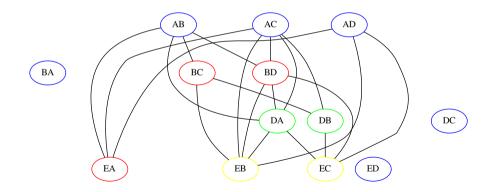


The chromatic number of graph is two.



#### A solution using the greedy heuristic

We can solve our original problem using a traffic light controller with four phases (one by each colour).



Discussion

From the previous solution to a real program.

### Graph colouring applications

The graph colouring problem has an important number of applications. For example:

- Scheduling problems (e.g. assigning jobs to time slots, assigning aircraft to flights, sports scheduling, exams time table)
- Register allocation
- Sudoku puzzles

# Analysis of Algorithms

Discussion

My program is better than yours. What does this means?

Discussion

My program is better than yours. What does this means?

Programs

Two contradictory goals: maintainability versus efficiency

### Discussion

My program is better than yours. What does this means?

### Programs

Two contradictory goals: maintainability versus efficiency

### Quote

'Programmers must not only be aware of ways of making programs run fast, but must know when to apply these techniques and when not to bother.' (p. 16)

Dependency

The running time of a program depends on factors as:

- 1. The input to the program.
- 2. The compiler used to create the program.
- 3. Features of set of instructions of machine.
- 4. The time complexity of the algorithm underlying the program.

Remark

That the running time depends of the input usually means it depends of the size of the input:

So, we shall use a function

$$T(n):\mathbb{N}\to\mathbb{R}^{\geq 0}$$

which will denote the running time of a program on inputs of size n.

Question

Have all the inputs of size n the same running time?

Question

Have all the inputs of size n the same running time?

No! The function T(n) is the worst-case running time of a program on inputs of size n.

### Question

Why not use a function

$$T_{\mathrm{avg}}(n): \mathbb{N} \to \mathbb{R}^{\geq 0}$$

which will denote the average running time of a program on inputs of size n?

### Question

Why not use a function

$$T_{\mathrm{avg}}(n): \mathbb{N} \to \mathbb{R}^{\geq 0}$$

which will denote the average running time of a program on inputs of size n?

Can you defined what is an average input for problem? (e.g. which is an average graph for the graph colouring problem?)

Remark

- The function T(n) has no measure units because it depends of a compiler and a set of instructions of machine.
- We can think in T(n) as the number of instructions executed on an idealised computer.
- If  $T(n) = n^2$  for some algorithm/program, we should talk about that the running time of the algorithm/program is proportional to  $n^2$ .

### Definition

Let  $g: \mathbb{N} \to \mathbb{R}^{\geq 0}$  be a function. We define the set of functions **big-oh of** g(n), denoted by O(g(n)), by

 $O(g(n)) := \{ f : \mathbb{N} \to \mathbb{R}^{\geq 0} \mid \text{there exist positive constants } c \in \mathbb{R}^+ \\ \text{and } n_0 \in \mathbb{Z}^+ \text{ such that } f(n) \leq cg(n) \\ \text{ for all } n \geq n_0 \}.$ 

### Definition

Let  $g: \mathbb{N} \to \mathbb{R}^{\geq 0}$  be a function. We define the set of functions **big-oh of** g(n), denoted by O(g(n)), by

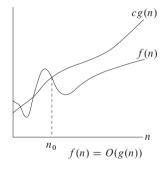
$$O(g(n)) := \{ f : \mathbb{N} \to \mathbb{R}^{\geq 0} \mid \text{there exist positive constants } c \in \mathbb{R}^+ \\ \text{and } n_0 \in \mathbb{Z}^+ \text{ such that } f(n) \leq cg(n) \\ \text{ for all } n \geq n_0 \}.$$

#### Notation

Both 'f(n) = O(g(n))' and 'f(n) is O(g(n))' mean that  $f(n) \in O(g(n))$ .

### Remark

If  $f(n) \in O(g(n))$  then function g(n) is an upper bound on the growth rate of the function f(n).\*



\*Figure source: Cormen, Leiserson, Rivest and Stein [2009, Fig. 3.1b]. Analysis of Algorithms

#### Exercise

Let  $T(n) = (n+1)^2$ . To prove that  $T(n) \in O(n^2)$ . Hint: Choose  $n_0 = 1$  and c = 4. (Example 1.4).

### Exercise

Let  $T(n) = (n + 1)^2$ . To prove that  $T(n) \in O(n^2)$ . Hint: Choose  $n_0 = 1$  and c = 4. (Example 1.4).

Question

If  $T(n) \in O(n^2)$  then  $T(n) \in O(n^3)$ ?

Example

See http://science.slc.edu/~jmarshall/courses/2002/spring/cs50/BigO/.

### Example

See http://science.slc.edu/~jmarshall/courses/2002/spring/cs50/BigO/.

Example

Note that

 $O(\log n) \subseteq O(\sqrt{n})$  $\subseteq O(n)$  $\subseteq O(n \log n)$  $\subseteq O(n^2)$  $\subseteq O(n^3)$  $\subseteq O(2^n).$ 

### Exercise

To prove that  $6n^2$  is not O(n). Hint: Use proof by contradiction.

### Theorem

Let d be a natural number and T(n) a polynomial function of degree d, that is,

$$T:\mathbb{N}
ightarrow\mathbb{R}$$
 $T(n)=\sum_{i=0}^{d}c_{i}n^{i}, \quad ext{with } c_{i}\in\mathbb{R} ext{ and } c_{d}
eq 0.$ 

If  $c_d > 0$  then  $T(n) \in O(n^d)$ .\*

<sup>\*</sup>See, e.g. [Cormen, Leiserson, Rivest and Stein 2009].

### Theorem

Let d be a natural number and T(n) a polynomial function of degree d, that is,

$$T:\mathbb{N}
ightarrow\mathbb{R}$$
 $T(n)=\sum_{i=0}^d c_i n^i, \quad ext{with } c_i\in\mathbb{R} ext{ and } c_d
eq 0.$ 

If 
$$c_d > 0$$
 then  $T(n) \in O(n^d)$ .\*

#### Example

$$T(n) = 42n^3 + 1523n^2 + 45728n \text{ is } O(n^3).$$

\*See, e.g. [Cormen, Leiserson, Rivest and Stein 2009].

Analysis of Algorithms

### Example

Since any constant is a polynomial of degree 0, any constant function is  $O(n^0)$ , i.e. O(1).

Remark

Note the missing variable in O(1).\*

<sup>\*</sup>We could use the  $\lambda$ -calculus notation, i.e.  $O(\lambda n.1)$ .

### Definition

Let  $g: \mathbb{N} \to \mathbb{R}^{\geq 0}$  be a function. We define the set of functions **big-omega of** g(n), denoted by  $\Omega(g(n))$ , by

 $\Omega(g(n)) := \{ f : \mathbb{N} \to \mathbb{R}^{\geq 0} \mid \text{there exist positive constants } c \in \mathbb{R}^+ \\ \text{and } n_0 \in \mathbb{Z}^+ \text{ such that } f(n) \geq cg(n) \\ \text{ for all } n \geq n_0 \}.$ 

### Definition

Let  $g: \mathbb{N} \to \mathbb{R}^{\geq 0}$  be a function. We define the set of functions **big-omega of** g(n), denoted by  $\Omega(g(n))$ , by

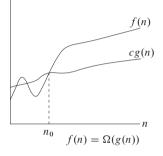
$$\Omega(g(n)) := \{ f : \mathbb{N} \to \mathbb{R}^{\geq 0} \mid \text{there exist positive constants } c \in \mathbb{R}^+ \\ \text{and } n_0 \in \mathbb{Z}^+ \text{ such that } f(n) \geq cg(n) \\ \text{ for all } n \geq n_0 \}.$$

#### Notation

Both ' $f(n) = \Omega(g(n))$ ' and 'f(n) is  $\Omega(g(n))$ ' mean that  $f(n) \in \Omega(g(n))$ .

### Remark

If  $f(n) \in \Omega(g(n))$  then function g(n) is a lower bound on the growth rate of the function f(n).\*



<sup>\*</sup>Figure source: Cormen, Leiserson, Rivest and Stein [2009, Fig. 3.1c]. Analysis of Algorithms

### Example

To prove that the function

$$T: \mathbb{N} \to \mathbb{R}^{\geq 0}$$
$$T(n) = \begin{cases} n, & \text{if } n \text{ is odd;} \\ n^2/100, & \text{if } n \text{ is even;} \end{cases}$$

is  $\Omega(n)$ . Hint: Choose c = 1/100 and  $n_0 = 1$ .

Theorem (the duality rule)  $T(n) \in \Omega(g(n)) \text{ iff } g(n) \in O(T(n)).$ 

### Remark

Note that the textbook uses an alternative definition for the big-omega notation.

Let  $g: \mathbb{N} \to \mathbb{R}^{\geq 0}$  be a function. The set of functions **big-omega of** g(n), denoted by  $\Omega(g(n))$ , is defined by

$$\Omega(g(n)) := \{ f : \mathbb{N} \to \mathbb{R}^{\geq 0} \mid \text{there exists a positive constant } c \in \mathbb{R}^+ \\ \text{such that } f(n) \geq cg(n) \text{ for an infinite} \\ \text{number of values of } n \}.$$

We prefer the previous definition introduced instead of the definition in the textbook because it is easier to work with it (e.g. it is transitive and it satisfies the duality rule).\*

<sup>\*</sup>See, e.g. Knuth [1976], Brassard and Bratley [1996] and Cormen, Leiserson, Rivest and Stein [2009]. Analysis of Algorithms

### Theorem (rule for sums)

Let  $T_1(n)$  and  $T_2(n)$  be  $O(g_1(n))$  and  $O(g_2(n))$ , respectively. Then

 $T_1(n) + T_2(n)$  is  $O(\max(g_1(n), g_2(n))).$ 

### Theorem (rule for sums)

Let  $T_1(n)$  and  $T_2(n)$  be  $O(g_1(n))$  and  $O(g_2(n))$ , respectively. Then

 $T_1(n) + T_2(n)$  is  $O(\max(g_1(n), g_2(n))).$ 

### Example

The function  $2^{n} + 3n^{2} + 15n$  is  $O(2^{n})$ .

### Theorem (rule for sums)

Let  $T_1(n)$  and  $T_2(n)$  be  $O(g_1(n))$  and  $O(g_2(n))$ , respectively. Then

 $T_1(n) + T_2(n)$  is  $O(\max(g_1(n), g_2(n))).$ 

### Example

The function  $2^{n} + 3n^{2} + 15n$  is  $O(2^{n})$ .

#### Exercise

To prove the rule for sums.

Theorem (rule for products)

Let  $T_1(n)$  and  $T_2(n)$  be  $O(g_1(n))$  and  $O(g_2(n))$ , respectively. Then

 $T_1(n)T_2(n)$  is  $O(g_1(n)g_2(n)).$ 

### Theorem (rule for products)

Let  $T_1(n)$  and  $T_2(n)$  be  $O(g_1(n))$  and  $O(g_2(n))$ , respectively. Then

 $T_1(n)T_2(n)$  is  $O(g_1(n)g_2(n)).$ 

### Example

Whiteboard.

### Theorem (rule for products)

Let  $T_1(n)$  and  $T_2(n)$  be  $O(g_1(n))$  and  $O(g_2(n))$ , respectively. Then

 $T_1(n)T_2(n)$  is  $O(g_1(n)g_2(n)).$ 

### Example

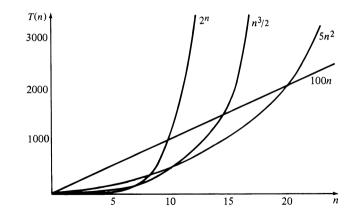
Whiteboard.

### Exercise

To prove the rule for products.

### Example

Running times of four programs.\*



### Example

Comparison of several running time functions (supposing that one instruction runs in one microsecond).

T(n)	n = 10	n = 50	n = 100	n = 1000
$\log n$	$3.3~\mu s$	$5.6~\mu s$	$6.4~\mu { m s}$	$9.9~\mu s$
n	$10.0~\mu { m s}$	$50.0~\mu { m s}$	$100.0~\mu { m s}$	$1.0 \; {\rm ms}$
$n^2$	100.0 $\mu {\tt s}$	$2.5 \; {\rm ms}$	$10.0 \; {\rm ms}$	1.0 s
$2^n$	$1.0 \; {\tt ms}$	35.8 y	4.0e16 y	$3.4\mathrm{e}287$ y
$3^n$	$59.0 \; {\tt ms}$	$2.3\mathrm{e}10$ y	$1.6\mathrm{e}34$ y	$4.2\mathrm{e}463$ y
n!	3.6 s	$9.7\mathrm{e}50$ y	$3.0\mathrm{e}144$ y	$1.3\mathrm{e}2554$ y

Definition

A **tractable problem** is a problem than can be solved by a computer algorithm that runs in polynomial-time.

Definition

A literal is an atomic formula (propositional variable) or the negation of an atomic formula.

Definition

A (propositional logic) formula F is in conjunctive normal form iff

F has the form  $F_1 \wedge \cdots \wedge F_n$ ,

where each  $F_1, \ldots, F_n$  is a disjunction of literals.

### Example (3-SAT: An intractable problem)

To determine the satisfiability of a propositional formula in conjunctive normal form where each disjunction of literals is limited to at most three literals.

The problem was proposed in Karp's 21 NP-complete problems [Karp 1972].

Improvements on 3-SAT deterministic algorithmic complexity\*

 $O(1.32793^n)$  Liu [2018]

- $O(1.3303^n)$  Makino, Tamaki and Yamamoto [2011, 2013]
- $O(1.3334^n)$  Moser and Scheder [2011]
- $O(1.439^n)$  Kutzkov and Scheder [2010]
- $O(1.465^n)$  Scheder [2008]
- $O(1.473^n)$  Brueggemann and Kern [2004]
- $O(1.481^n)$  Dantsin, Goerdt, Hirsch, Kannan, Kleinberg, Papadimitriou, Raghavan and Schöning [2002]
- $O(1.497^n)$  Schiermeyer [1996]
- $O(1.505^n)$  Kullmann [1999]
- $O(1.6181^n)$  Monien and Speckenmeyer [1979, 1985]
  - Brute-force search

 $O(2^n)$ 

<sup>\*</sup>Main sources: Hertli [2011, 2015]. Last updated: June 2019.

Supercomputers

Machines from: www.top500.org\* PetaFLOP (PFLOP):  $10^{15}$  floating-point operations per second

Date	Machine	PFLOPs
2019-06	Summit	148.60
2018-11	Summit	143.50
2018-06	Summit	122.30
2016-06	Sunway TaihuLight	93.01
2013-06	Tianhe-2	33.86
2012-06	Blue Gene/Q	16.32
2011-06	K computer	8.16

\*Last updated: TOP500 List - June 2019.

Simulation

Running 3-SAT times on different supercomputers using the faster deterministic algorithm, i.e.  $T(1.32793^n).$ 

Machine	PFLOPs	n = 150	n = 200	n = 400
Summit (2019-06)	148.60	$20.1~{ m s}$	$336.1~{\rm d}$	4.0e24 y
Summit (2018-11)	143.50	$20.8~{\rm s}$	$348.1 \ {\rm d}$	$4.1\mathrm{e}24$ y
Summit (2018-06)	122.30	$24.5~{ m s}$	1.1 y	$4.8\mathrm{e}24$ y
Sunway TaihuLight	93.01	$32.2~{\rm s}$	1.5 y	$6.4\mathrm{e}24$ y
Tianhe-2	33.86	$1.5 \ { m m}$	$4.1 \ y$	$1.7\mathrm{e}25$ y
Blue Gene/Q	16.32	$3.1~{\rm m}$	8.4 y	$3.6\mathrm{e}25$ y
K computer	8.16	$6.1~{\rm m}$	16.8 y	$7.3\mathrm{e}25$ y

Simulation

Running 3-SAT times for different deterministic algorithms using the faster supercomputer, i.e.  $148.60\ {\rm PFLOPs}.$ 

Complexity	n = 150	n = 200	n = 400
$T(1.32793^n)$	$20.1~{ m s}$	$336.1~{ m d}$	4.0e24 y
$T(1.3303^{n})$	$26.3 \ \mathrm{s}$	1.3 у	$8.1\mathrm{e}24$ y
$T(1.3334^{n})$	$37.3~{ m s}$	2.1 y	$2.1\mathrm{e}25$ y
$T(1.439^{n})$	$39.9~{\rm d}$	8.7e6 y	3.6е38 у
$T(1.465^{n})$	1.6 y	3.1e8 y	$4.6\mathrm{e}41$ y
$T(2^n)$	$3.1\mathrm{e}20$ y	$3.4\mathrm{e}35$ y	$5.5\mathrm{e}95$ y

# Calculating the Running Time of a Program

### General rules for the analysis of programs

The running time of

- 1. each assignment, read, and write statement is O(1),
- 2. a sequence of statements is the largest running time of any statement in the sequence (rule for sums),
- 3. evaluate conditions is O(1),
- 4. an if-statement is the cost of evaluate the condition plus the running time of the body of the if-statement (worst case running time).
- 5. an if-then-else construct is the cost of evaluate the condition plus the larger running time of the true-body and the else-body (worst case running time).
- 6. a loop is the sum, over all times around the loop, of the running time of the body plus the cost of evaluate the termination condition.

# Calculating the Running Time of a Program

### Example (whiteboard)

Worst case running time of first version of bubble sort.

# Calculating the Running Time of a Program

### Example (whiteboard)

Worst case running time of the MYSTERY function (Exercise 1.12b).

 $\operatorname{Mystery}(n:\mathbb{N})$ 

- 1 for i := 1 to n 1
- 2 **for** j := i + 1 **to** n
  - for k := 1 to j

Some statement requiring O(1) time.

3

4

General rules for the analysis of programs (continuation)

7. For calculating the running time of programs which call non-recursive procedures/functions, we calculate first the running time of these non-recursive procedures/functions.

### Example (whiteboard)

Worst case running time of second version of bubble sort.

General rules for the analysis of programs (continuation)

8. For calculating the running time of recursive programs, we get a recurrence for T(n) (i.e. an equation for T(n)) and we solve the recurrence.

#### Example (whiteboard)

Worst case running time of the  $\ensuremath{\operatorname{FACTORIALR}}$  function.

### Example (whiteboard)

Worst case running time of the BUGGY function (Exercise 1.12d).

 $\operatorname{BUGGY}(n:\mathbb{N})$ 

- 1 if  $n \leq 1$
- 2 **return** 1
- 3 **else**
- 4 return (BUGGY(n-1) + BUGGY(n-1))

### Example (whiteboard)

Worst case running time of the BUGGY function (Exercise 1.12d).

 $\operatorname{BUGGY}(n:\mathbb{N})$ 

- 1 if  $n \leq 1$
- 2 **return** 1
- 3 **else**

4 return 
$$(BUGGY(n-1) + BUGGY(n-1))$$

### Question

Why is the function buggy?

#### Exercise

The  $MAX(i : \mathbb{N}, n : \mathbb{N})$  function returns the largest element in positions i through i + n - 1 of an integer array A. You may assume for convenience that n is a power of 2. Let T(n) be the worst-case time taken by the MAX function with second argument n. That is, n is the number of elements of which the largest is found. Give, using the big-oh notation the worst case running time of the MAX function (Exercise 1.18).

### Exercise (continuation)

 $MAX(i:\mathbb{N},n:\mathbb{N})$  $m_1, m_2:\mathbb{Z}$ 1 2 **if** n == 13 return *A*[*i*] 4 else 5  $m_1 := MAX(i, |n/2|)$ 6  $m_2 := \max(i + \lfloor n/2 \rfloor, \lfloor n/2 \rfloor)$ 7 if  $m_1 < m_2$ 8 return  $m_2$ 9 else 10 return  $m_1$ 

#### Definition

'We can think of an **abstract data type** (ADT) as a mathematical model with a collection of operations defined on that model.' (p. 13)

#### Definition

'The data type of a variable is the set of values that the variable may assume.' (p. 13)

#### Definition

**Data structures** 'are collections of variables, possibly of several different data types, connected in various ways.' (p. 13)

#### Some remarks

- Abstract data type is a theoretical concept (design and analisis of algorithms).
- Data structures are concrete representations of data (implementation of algorithms).
- ADTs are implemented by data structures.

#### Some remarks

- Abstract data type is a theoretical concept (design and analisis of algorithms).
- Data structures are concrete representations of data (implementation of algorithms).
- ADTs are implemented by data structures.

#### Example

Data types: Bool, char, integer, float and double

Data structures: Arrays and records

ADTs: Graphs, lists, queues, sets, stacks and trees

Advantages of using abstract data types

• Generalisation

'ADT's are generalizations of primitive data types (integer, real, and so on), just as procedures are generalizations of primitive operations (+, -, and so on).' (p. 11).

• Encapsulation

'The ADT encapsulates a data type in the sense that the definition of the type and all operations on that type can be localized to one section of the program.' (p. 11).

### Definition

A list is a sequence of zero or more elements of a given type

```
a_1, a_2, ..., a_n
```

where,

- n: length of the list, if n == 0 then the list is empty,
- $a_1$ : first element of the list,
- $a_n$ : last element of the list,
- the element  $a_i$  is in the position i, and

elements are linearly ordered according to their position on the list.

#### Operations on lists

• END(L)

Returns the position following position n in an n-element list L.

#### Operations on lists

• END(L)

Returns the position following position n in an n-element list L.

• INSERT(x, p, L)

Inserts x at position p in list L:

$$a_1, a_2, \dots, a_n \to a_1, a_2, \dots, a_{p-1}, x, a_{p+1}, \dots, a_n$$

If p is END(L), then

$$a_1, a_2, \ldots, a_n \to a_1, a_2, \ldots, a_n, x$$

If list L has no position p, the result is undefined.

(continued on next slide)

#### Abstract Data Types

Operations on lists (continuation)

• LOCATE(x, L)

Returns the position of x on list L.

If x appears more than once, then the position of the first occurrence is returned. If x does not appear at all, then END(L) is returned.

### Operations on lists (continuation)

• LOCATE(x, L)

Returns the position of x on list L.

If x appears more than once, then the position of the first occurrence is returned. If x does not appear at all, then END(L) is returned.

• Retrieve(p, L)

Returns the element at position p on list L.

The result is undefined if p == END(L) or if L has no position p.

#### (continued on next slide)

### Operations on lists (continuation)

•  $\operatorname{NEXT}(p, L)$  and  $\operatorname{PREVIOUS}(p, L)$ 

Return the positions following and preceding position p on list L.

If p is the last position on L, then NEXT(p, L) = END(L). NEXT is undefined if p is END(L). PREVIOUS is undefined if p is 1. Both functions are undefined if L has no position p.

### Operations on lists (continuation)

• NEXT(p, L) and PREVIOUS(p, L)

Return the positions following and preceding position p on list L.

If p is the last position on L, then NEXT(p, L) = END(L). NEXT is undefined if p is END(L). PREVIOUS is undefined if p is 1. Both functions are undefined if L has no position p.

• Delete(p, L)

Deletes the element at position p of list L:

$$a_1, a_2, \dots, a_n \to a_1, a_2, \dots, a_{p-1}, a_{p+1}, \dots, a_{n-1}$$

The result is undefined if L has no position p or if p = END(L).

(continued on next slide)

Operations on lists

• MakeNull(L)

Causes L to become an empty list and returns position END(L).

#### Operations on lists

• MakeNull(L)

Causes L to become an empty list and returns position END(L).

• FIRST(L)

Returns the first position on list L.

If L is empty, the position returned is END(L).

#### Operations on lists

• MakeNull(L)

Causes L to become an empty list and returns position END(L).

• FIRST(L)

Returns the first position on list L.

If L is empty, the position returned is END(L).

• PRINTLIST(L)

Prints the elements of L in the order of occurrence.

### Example

A procedure for removing all duplicates of a list (from Fig 2.1).

PURGE(L:List)

1  $\triangleright$  Removes duplicate elements from list *L*.

```
2 p := \text{First}(L)
```

```
3 while p <> END(L)
```

```
4 q := \operatorname{NEXT}(p, L)
```

5 while q <> END(L)6 if SAME(RETRI

```
if SAME(RETRIEVE(p, L), RETRIEVE(q, L))
DELETE(q, L)
```

else

```
9 q := \text{NEXT}(q, L)
10 p := \text{NEXT}(p, L)
```

7

8

#### Exercise

Suppose that the list operations and the SAME function are O(1). To give the worst case running time of the PURGE procedure. Hint: To suppose that the list has n elements.

#### Exercise

'The following procedure was intended to remove all occurrences of element x from list L. Explain why it doesn't always work and suggest a way to repair the procedure so it performs its intended task.' (Exercise 2.9)

DELETE(x : ElementType, L : List)

- $1 \quad p: \text{ElementType}$
- 2 p := FIRST(L)
- 3 while p <> END(L)
- 4 **if** RETRIEVE(p, L) == x
  - DELETE(p, L)
- $6 \qquad p := \operatorname{NEXT}(p, L)$

5

Definition

'A **stack** is a special kind of list in which all insertions and deletions take place at one end, called the **top**.' (p. 53).

#### Definition

'A **stack** is a special kind of list in which all insertions and deletions take place at one end, called the **top**.' (p. 53).

#### Remark

Stacks are also named LIFO (last-input-first-output) lists.

#### Definition

'A **stack** is a special kind of list in which all insertions and deletions take place at one end, called the **top**.' (p. 53).

#### Remark

Stacks are also named LIFO (last-input-first-output) lists.

#### Example

Whiteboard.

#### Operations on stacks

- MAKENULL(S). Makes stack S be an empty stack.
- TOP(S). Returns the element at the top of stack S.
- POP(S). Deletes the top element of the stack.
- PUSH(x, S). Inserts the element x at the top of stack S.
- EMPTY(S). Returns true if S is an empty stack; return false otherwise.

### Example

Program for processing a line by a text editor using a stack (Example 2.2).

Special characters:

• The character '#' is the erase character (back-space key) which cancel the previous uncanceled character, e.g.,

abc#d##e is ae.

• The character '@' is the kill character which cancel all previous characters on the current line.

Example (continuation)	
EDIT()	
1	$S: \mathrm{Stack}$
2	$c: \operatorname{Char}$
3	$\mathrm{MAKENULL}(S)$
4	while not <i>eoln</i>
5	$\operatorname{read}(c)$
6	if $c == '\#'$
7	$\operatorname{POP}(S)$
8	elseif $c == `@'$
9	$\mathrm{MAKENULL}(S)$
10	else
11	$\triangleright$ The character $c$ is an ordinary character.
12	$\operatorname{PUSH}(c,S)$
13	print $S$ in reverse order

#### Definition

'A **queue** is another special kind of list, where items are inserted at one end (the **rear**) and deleted at the other end (the **front**).' (p. 56)

#### Definition

'A **queue** is another special kind of list, where items are inserted at one end (the **rear**) and deleted at the other end (the **front**).' (p. 56)

#### Remark

Queues are also named FIFO (first-input-first-output) lists.

#### Definition

'A **queue** is another special kind of list, where items are inserted at one end (the **rear**) and deleted at the other end (the **front**).' (p. 56)

#### Remark

Queues are also named FIFO (first-input-first-output) lists.

#### Example

Whiteboard.

#### Operations on queues

- MAKENULL(Q). Makes queue Q an empty list.
- $\operatorname{FRONT}(Q)$ . Returns the first element on queue Q.
- ENQUEUE(x, Q). Inserts element x at the end of queue Q.
- ${\ensuremath{\, \circ }}$   ${\ensuremath{\rm DEQUEUE}}(Q).$  Deletes the first element of Q
- $\operatorname{EMPTY}(Q)$ . Returns true iff Q is an empty queue.

#### Queue operations on terms of list operations

We can use list operations for defining queue operations.

$$\begin{aligned} & \operatorname{FRONT}(Q) := \operatorname{RETRIEVE}(\operatorname{FIRST}(Q), Q), \\ & \operatorname{ENQUEUE}(x, Q) := \operatorname{INSERT}(x, \operatorname{END}(Q), Q), \\ & \operatorname{DEQUEUE}(Q) := \operatorname{DELETE}(\operatorname{FIRST}(Q), Q). \end{aligned}$$

# Appendix

### Floor and Ceiling Functions

#### Definition

The **floor** function is defined by

$$\lfloor \cdot \rfloor : \mathbb{R} \to \mathbb{Z}$$
$$\lfloor x \rfloor := \text{that unique integer } n \text{ such that } n \leq x < n+1.$$

#### Definition

The **ceiling** function is defined by

$$\lceil \cdot \rceil : \mathbb{R} \to \mathbb{Z}$$
$$\lceil x \rceil := \text{that unique integer } n \text{ such that } n-1 < x \leq n.$$

#### Definition

Let  $a_1, a_2, \ldots, a_n$  be a sequence of numbers, where n is a positive integer. Recall the inductive definition of the summation notation:

$$\sum_{k=1}^{n} a_k := a_1,$$
  
$$\sum_{k=1}^{n} a_k := \left(\sum_{k=1}^{n-1} a_k\right) + a_n$$
  
$$= a_1 + a_2 + \dots + a_{n-1} + a_n.$$

#### Properties

$$\sum_{k=1}^{n} (a_k + b_k) = \sum_{k=1}^{n} a_k + \sum_{k=1}^{n} b_k$$
$$\sum_{k=1}^{n} ca_k = c \sum_{k=1}^{n} a_k$$
$$\sum_{k=1}^{n} (\alpha a_k + \beta b_k) = \alpha \sum_{k=1}^{n} a_k + \beta \sum_{k=1}^{n} b_k$$

(additive property),

(homogeneous property),

(linearity property).

#### Properties

$$\sum_{k=1}^{n} f(n) = nf(n),$$
$$\sum_{k=1}^{n} a_k = \sum_{k=1}^{i} a_k + \sum_{k=i+1}^{n} a_k.$$

#### Properties

$$\sum_{k=1}^{n} k = \frac{n(n+1)}{2},$$
$$\sum_{k=1}^{n} k^2 = \frac{n(n+1)(2n+1)}{6},$$
$$\sum_{k=1}^{n} k^3 = \left(\frac{n(n+1)}{2}\right)^2.$$

- Aho, A. V., Hopcroft, J. E. and Ullman, J. D. [1983] (1985). Data Structures and Algorithms. Reprinted with corrections. Addison-Wesley (cit. on p. 3).
- Bondy, J. A. and Murty, U. S. R. (2008). Graph Theory. Springer-Verlag (cit. on pp. 42–46).
  - Brassard, G. and Bratley, P. (1996). Fundamentals of Algorithmics. Prentice Hall (cit. on pp. 3, 31, 90).
  - Brueggemann, T. and Kern, W. (2004). An Improved Deterministic Local Search Algorithm for 3-SAT. Theoretical Computer Science 329.1–3, pp. 303–313. DOI: 10.1016/j.tcs.2004.08.002 (cit. on p. 102).
  - Cormen, T. H., Leiserson, C. E., Rivest, R. L. and Stein, C. [1990] (2009). Introduction to Algorithms. 3rd ed. MIT Press (cit. on pp. 25, 76, 82, 83, 87, 90).
- Dantsin, E. et al. (2002). A Deterministic  $(2 2/(k + 1))^n$  Algorithm for k-SAT Based on Local Search. Theoretical Computer Science 289.1, pp. 69–83. DOI: 10.1016/S0304-3975(01)00174-8 (cit. on p. 102).
  - Diestel, R. [1997] (2017). Graph Theory. 5th ed. Springer. DOI: 10.1007/978-3-662-53622-3 (cit. on pp. 39-41).

- Hertli, T. (2011). 3-SAT Faster and Simpler Unique-SAT Bounds for PPSZ Hold in General. In: Proceedings of the 52nd Annual Symposium on Foundations of Computer Science (FOCS 2011). IEEE, pp. 277–284. DOI: 10.1109/FOCS.2011.22 (cit. on p. 102).
- (2015). Improved Exponential Algorithms for SAT and CISP. PhD thesis. ETH Zurich. DOI: 10.3929/ethz-a-010512781 (cit. on p. 102).
- Karp, R. M. (1972). Reducibility Among Combinatorial Problems. In: Complexity of Computer Computations. Ed. by Miller, R. E. and Thatcher, J. W. Plenum Press, pp. 85–103. DOI: 10.1007/ 978-1-4684-2001-2\_9 (cit. on p. 101).
- Knuth, D. E. (1976). Big Omicron and Big Omega and Big Theta. SIGACT News 8.2, pp. 18–24. DOI: 10.1145/1008328.1008329 (cit. on p. 90).
- Kullmann, O. (1999). New Methods for 3-SAT Decision and Worst-Case Analysis. Theoretical Computer Science 223.1–2, pp. 1–72. DOI: 10.1016/S0304-3975(98)00017-6 (cit. on p. 102).
- Kutzkov, K. and Scheder, D. (2010). Using CSP to Improve Deterministic 3-SAT. CoRR abs/1007.1166 URL: https://arxiv.org/abs/1007.1166 (cit. on p. 102).

- Liu, S. (2018). Chain, Generalization of Covering Code, and Deterministic Algorithm for *k*-SAT. In: 45th International Colloquium on Automata, Languages, and Programming (ICALP 2018). Ed. by Chatzigiannakis, I., Kaklamanis, C., Marx, D. and Sannella, D. Vol. 107. Leibniz International Proceedings in Informatics (LIPIcs), 88:1–88:13. DOI: 10.4230/LIPIcs.ICALP.2018.88 (cit. on p. 102).
- Makino, K., Tamaki, S. and Yamamoto, M. (2011). Derandomizing HSSW Algorithm for 3-SAT. In: Computing and Combinatorics (COCOON 2011). Ed. by Fu, B. and Du, D.-Z. Vol. 6842. Lecture Notes in Computer Science. Springer, pp. 1–12. DOI: 10.1007/978-3-642-22685-4\_1 (cit. on p. 102).
  - (2013). Derandomizing HSSW Algorithm for 3-SAT. Algorithmica 67.2, pp. 112–124. DOI: 10.1007/s00453-012-9741-4 (cit. on p. 102).
  - Monien, B. and Speckenmeyer, E. (1979). 3-Satisfiability is Testable in  $O(1.62^r)$  Steps. Tech. rep. 3/1979. Reihe Theoretische Informatik, Universität Gesamthochschule Paderborn (cit. on p. 102).
    - (1985). Solving Satisfiability in less than  $2^n$  Steps. Discrete Applied Mathematics 10.3, pp. 287–295. DOI: 10.1016/0166-218X(85)90050-2 (cit. on p. 102).

- Moser, R. A. and Scheder, D. (2011). A Full Derandomization of Schöning's *k*-SAT Algorithm. In: Proceedings of the Forty-third Annual ACM Symposium on Theory of Computing (STOC 2011), pp. 245–252. DOI: 10.1145/1993636.1993670 (cit. on p. 102).
  - Parberry, I. and Gasarch, W. [1994] (2002). Problems on Algorithms. 2nd ed. Prentice Hall (cit. on pp. 3, 30).
- Scheder, D. (2008). Guided Search and a Faster Deterministic Algorithm for 3-SAT. In: Proc. of the 8th Latin American Symposium on Theoretical Informatic (LATIN 2008). Ed. by Laber, E. S., Bornstein, C., Nogueira, T. L. and Faria, L. Vol. 4957. Lecture Notes in Computer Science. Springer, pp. 60–71. DOI: 10.1007/978-3-540-78773-0\_6 (cit. on p. 102).
  - Schiermeyer, I. (1996). Pure Literal Look Ahead: An  $O(1.497^n)$  3-Satisfability Algorithm (Extended Abstract). Workshop on the Satisfability Problem, Siena 1996. URL: http://gauss.ececs.uc.edu/franco\_files/SAT96/sat-workshop-abstracts.html (cit. on p. 102).