IMPLEMENTATION OF INTERVAL VALUED OPTIMIZATION TECHNIQUES APPLIED TO PARAMETER ESTIMATION UNDER UNCERTAINTY

Jose D. Gallego-Posada
jgalle29@eafit.edu.co
Maria E. Puerta-Yepes
mpuerta@eafit.edu.co
Maria E. Puerta-Yepes
mpuerta@eafit.edu.co
Functional Analysis and Applications Research Group

## Mathematical Engineering

CB0441 - Research Practice 2
Progress Report
April 10 ${ }^{\text {th }}, 2015$

UNIVERSIDAD
EAFIT

1 The Interval Number System
2 Operations of Interval Arithmetic
3 Limits and Continuity

4 Optimization Problem Formulation - KKT Conditions
5 Order Relations for Intervals
6 Parameter Estimation

7 Next Challenges

8 References

## UNIVERSIPAD

## Definition - Notation

Consider the closed interval denoted by $[a, b]$ which represents the set of real numbers given by

$$
[a, b]=\{x \in(R): a \leq x \leq b\}
$$

Define $I(\mathbb{R}):=\{[a, b]: a \leq b, a, b \in \mathbb{R}\}$ be the set of all closed intevals of $\mathbb{R}$. We say a interval $[a, b]$ is degenerate if $a=b$.

We adopt the infimum-supremum notation for intervals:

$$
\begin{aligned}
& X=\left[X^{L}, X^{U}\right] \text { with } X^{L}, X^{U} \in \mathbb{R} \\
& X=Y \text { if } X^{L}=Y^{L} \wedge X^{U}=Y^{U}
\end{aligned}
$$

## UNIVERSIDAD EAFIT.

## Relevance of Intersection

Intersection plays a key role in interval analysis. If we have two intervals containing a result of interest - regardless of how they were obtained - then the intersection, which may be narrower, also contains the result.


Figure 1: Intersection of measurements.

## The Interval Number System

## UNIVERSIDAD <br> EAFIT

## Width, Absolute Value, Midpoint (I)

## Length

$$
I(X):=X^{U}-X^{L}
$$

## Absolute Value

$$
|X|:=\max \left\{\left|X^{L}\right|,\left|X^{U}\right|\right\}
$$

Midpoint

$$
m(X):=\frac{1}{2}\left(X^{L}+X^{U}\right)
$$

## UNIVERSIDAD EAFIT

## Width, Absolute Value, Midpoint (II)



Figure 2: Width, absolute value, and midpoint of an interval.

## Definition of Arithmetic Operations

Let $\odot \in\{+,-, \cdot, /\}$ be a binary operation in the real numbers, e.g., addition, substraction, multiplication and division.

$$
X \odot Y:=\{x \odot y: x \in X, y \in Y\}
$$

In order to simplify notation, the interval $[x, x]$ will be referred as the real number $x$ itself, whenever the context is clear.

## UNIVERSIDAD EAFIT

## Endpoint Formulas for the Arithmetic Operations

Let $X, Y \in I(\mathbb{R})$. It can be shown that:

1. $X+Y=\left[X^{L}+Y^{L}, X^{U}+Y^{U}\right]$ Example
2. $-Y=\left[-Y^{U},-Y^{L}\right]$ Example
3. $X-Y=X+(-Y)=\left[X^{L}-Y^{U}, X^{U}-Y^{L}\right]$

Example
4. $k X=\left[k X^{L}, k X^{U}\right]$ Example
5. $X Y=[\min S, \max S]$, where

$$
\begin{equation*}
S=\left\{X^{L} Y^{L}, X^{L} Y^{U}, X^{U} Y^{L}, X^{U} Y^{U}\right\} \tag{Example}
\end{equation*}
$$

6. $1 / Y=\left[1 / Y^{U}, 1 / Y^{L}\right]$
7. $X / Y=X \cdot(1 / Y)$ Example

## Hukuhara Difference

## Difference

Let $X=\left[X^{L}, X^{U}\right]$ and $Y=\left[Y^{L}, Y^{U}\right]$ be two closed intervals in $\mathbb{R}$. If $X^{L}-Y^{L} \leq X^{U}-Y^{U}$, then the Hukuhara difference $Z=X \ominus Y$ exists and $Z=\left[Z^{L}, Z^{U}\right]=\left[X^{L}-Y^{L}, X^{U}-Y^{U}\right]$.

## Note

The usual substraction and the Hukuhara difference betwen two intervals need not be the same:

$$
\left[X^{L}-Y^{U}, X^{U}-Y^{L}\right]=X-Y \neq X \ominus Y=\left[X^{L}-Y^{L}, X^{U}-Y^{U}\right]
$$

## UNIVERSIDAD <br> EAFIT

## Hausdorff Metric

Let $X, Y \subseteq \mathbb{R}^{n}$. Then the Hausdorff metric between $X$ and $Y$ is defined by

$$
d_{H}(X, Y)=\max \left\{\sup _{x \in X} \inf _{y \in Y}\|x-y\|, \sup _{y \in Y} \inf _{x \in X}\|x-y\|\right\}
$$

where $\|\cdot\|$ is a norm in $\mathbb{R}^{n}$.
If $X=\left[X^{L}, X^{U}\right]$ and $Y=\left[Y^{L}, Y^{U}\right]$ are two closed intervals in $\mathbb{R}$, it is not hard to see that

$$
d_{H}(X, Y)=\max \left\{\left|X^{L}-Y^{L}\right|,\left|X^{U}-Y^{U}\right|\right\}
$$

## Convergence

## Convergence in $/(\mathbb{R})$

Let $\left\{X_{n}\right\}$ and $X \in I(\mathbb{R})$. We say that the sequence of intervals $\left\{X_{n}\right\}$ converges to $X$, denoted by $\lim _{n \rightarrow \infty} X_{n}=X$, if, for every $\epsilon>0$, there exists $N \in \mathbb{N}$, such that, for $n \geq N$, we have $d_{H}\left(X_{n}, X\right)<\epsilon$.

Lemma

$$
\lim _{n \rightarrow \infty} X_{n}=X \text { if and only if } X_{n}^{L} \rightarrow X^{L} \wedge X_{n}^{U} \rightarrow X^{U}
$$

## Functions in $I(\mathbb{R})(I)$

## Interval-valued Function

The function $f: \mathbb{R}^{n} \rightarrow I(\mathbb{R})$ defined on an Eucliden space $\mathbb{R}^{n}$ is called an interval-valued function. This function can also be written as $f(x)=\left[f^{L}(x), f^{U}(x)\right]$, where $f^{L}$ and $f^{U}$ are real-valued functions defined on $\mathbb{R}^{n}$ and satisfy $f^{L}(x) \leq f^{U}(x)$ for every $x \in \mathbb{R}^{n}$.

## Limit of a Function

For $\mathbb{C} \in \mathbb{R}^{n}$ we write $\lim _{\mathbb{x} \rightarrow \mathbb{C}} f(x)=X$ if, for every $\epsilon>0$, there exists $\delta>0$ such that, for $\|\mathfrak{x}-\mathbb{C}\|<\delta$, we have $d_{H}(f(x), X)<\epsilon$.

## Functions in $/(\mathbb{R})(I I)$

## Lemma

Let $f$ be an interval-valued function defined on $\mathbb{R}^{n}$ and $X=\left[X^{L}, X^{U}\right]$ be an interval in $\mathbb{R}$. Then $\lim _{x \rightarrow \mathbb{C}} f\left(x^{x}\right)=X$ if and only if $\lim _{x \rightarrow \mathbb{C}} f^{L}(x)=X^{L}$ and $\lim _{x \rightarrow \mathbb{C}} f^{U}(x)=X^{U}$.

## Continuity

Let $f$ be an interval-valued function defined on $\mathbb{R}^{n}$. We say that $f$ is continuous at $\mathbb{C} \in \mathbb{R}^{n}$ if

$$
\lim _{\mathfrak{x} \rightarrow \mathbb{C}} f(\mathfrak{x})=f(\mathbb{C})
$$

## universidad <br> EAFIT

## Example



Figure 3: Graphic representation $f(x)=\left[x^{2}+x+1, x^{2}+3\right]$.

## Optimization Problem Formulation - KKT Conditions

## UNIVERSIDAD <br> EAFIT

## Optimization Problems

## Problem (RVOP)

$$
\begin{gathered}
\min \quad f(x)=f\left(x_{1}, \ldots, x_{n}\right) \\
\text { subject to } g_{i}(x) \leq 0
\end{gathered}
$$

## Problem (IVOP)

$$
\begin{gathered}
\min f(x)=\left[f^{L}\left(x_{1}, \ldots, x_{n}\right), f^{U}\left(x_{1}, \ldots, x_{n}\right)\right]=\left[f^{L}(x), f^{U}(x)\right] \\
\text { subject to } g_{i}(x) \leq 0
\end{gathered}
$$

## Order Relations

Let $X=\left[X^{L}, X^{U}\right]$ and $Y=\left[Y^{L}, Y^{U}\right] \in I(\mathbb{R})$. It is possible to express $X$ as a function of its center and width, as $X=\langle m(X), w(X)\rangle$.

## Order Relations

$$
\begin{gathered}
X \preceq\left\llcorner U Y \text { if and only if } X^{L} \leq Y^{L} \text { and } X^{U} \leq Y^{U}\right. \\
X \preceq c w Y \text { if and only if } m(X) \leq m(Y) \text { and } w(X) \leq w(Y) \\
X \preceq u c Y \text { if and only if } X^{U} \leq Y^{U} \text { and } m(X) \leq m(Y)
\end{gathered}
$$

## Solution Types

## Type-I

Let $x^{*}$ be a feasible solution, i.e., $x^{*} \in X$. We say that $x^{*}$ is a type-I solution of problem (IVOP) if there exists no $\bar{x} \in X$ such that $f(\overline{\mathrm{x}}) \prec\left\llcorner U f\left(\mathrm{x}^{*}\right)\right.$.

## Type-II

Let ${x^{*}}^{\text {be }}$ a feasible solution, i.e., $x^{*} \in X$. We say that $x^{*}$ is a type-Il solution of problem (IVOP) if there exists no $\bar{x} \in X$ such that $f(\overline{\mathrm{x}}) \prec L U f\left(\mathrm{x}^{*}\right)$ or $f(\overline{\mathrm{x}}) \prec C W f\left(\mathrm{x}^{*}\right)$.

## KKT Conditions - Real Case

## Theorem

Assume that the constraint functions $g_{i}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ are convex on $\mathbb{R}^{n}$ for $i=1, \ldots, m$. Let $X=\left\{火 \in \mathbb{R}^{n}: g_{i}(\mathbb{x}) \leq 0, i=1, \ldots, m\right.$ be a feasible set and a point $x^{*} \in X$. Suppose that the objective function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex at $火^{*}$, and $f, g_{i}, i=1, \ldots m$, are continuously differentiable at $\mathfrak{k}^{*}$. If there exist (Langrange) multipliers $0 \leq \mu_{i} \in$ $\mathbb{R}, i=1, \ldots, m$, such that

1. $\nabla f\left(\mathfrak{k}^{*}\right)+\sum_{i=1}^{m} \mu_{i} \nabla g_{i}\left(\mathfrak{x}^{*}\right)=0$
2. $\mu_{i} g_{i}\left(x^{*}\right)=0$ for all $i=1, \ldots, m$.
then $x^{*}$ is an optimal solution of problem (RVOP).

## KKT Conditions - Interval-valued Case

## Theorem

Suppose that the the real-valued constraint functions $g_{i}, i=1, \ldots, m$, of problem (IVOP) satisfy the KKT assumptions at $x^{*}$ and the interval-valued objective function $f: \mathbb{R}^{n} \rightarrow I(\mathbb{R})$ is LU-convex and weakly continuously differentiable at $\mathfrak{k}^{*}$. If there exist (Langrange) multipliers $0<\lambda^{L}, \lambda^{U} \in R$ and $0 \leq \mu_{i} \in \mathbb{R}, i=1, \ldots, m$, such that

$$
\begin{aligned}
& \text { 1. } \lambda^{L} \nabla f^{L}\left(\mathfrak{x}^{*}\right)+\lambda^{U} \nabla f^{U}\left(x^{*}\right)+\sum_{i=1}^{m} \mu_{i} \nabla g_{i}\left(\mathfrak{x}^{*}\right)=0 \\
& \text { 2. } \mu_{i} g_{i}\left(\mathfrak{x}^{*}\right)=0 \text { for all } i=1, \ldots, m \text {. }
\end{aligned}
$$

then $x^{*}$ is a type-I and type-II solution of problem (IVOP).

## Parameter Estimation

## UNIVERSIDAD EAFIT:

## Interval-Valued Polynomial

## Interval-Valued Polynomial

Let $c_{i}=\left[c_{i}^{L}, c_{i}^{U}\right] \in I(\mathbb{R})$ for $i \in \mathbb{N}$. We say $p(x)$ is an interval-valued polynomial if it can be expressed in the form

$$
p(x)=\sum_{i=0}^{n} c_{i} \cdot x^{i}=\sum_{i=0}^{n}\left[c_{i}^{L}, c_{i}^{U}\right] \cdot x^{i}
$$

## Parameter Estimation

## UNIVERSIDAD 콥․․․․

## Matrix Representation

## Vandermonde Matrix

Let $c_{i}=\left[c_{i}^{L}, c_{i}^{U}\right] \in I(\mathbb{R})$ for $i \in\{1, \ldots, n\}$.

$$
\begin{gathered}
{\left[\begin{array}{c}
y_{1} \\
\vdots \\
y_{m}
\end{array}\right]=\left[\begin{array}{ccccc}
1 & x_{1} & x_{1}^{2} & \cdots & x_{1}^{n} \\
1 & x_{2} & x_{2}^{2} & \cdots & x_{2}^{n} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
1 & x_{m} & x_{m}^{2} & \cdots & x_{m}^{n}
\end{array}\right]\left[\begin{array}{c}
c_{0} \\
\vdots \\
c_{n}
\end{array}\right]+\left[\begin{array}{c}
\varepsilon_{0} \\
\vdots \\
\varepsilon_{n}
\end{array}\right]} \\
\mathscr{V}=\mathbb{C}+\mathbb{E}
\end{gathered}
$$

In this case, $\mathbb{V}$ is called a Vandermonde matrix.

## Parameter Estimation

## UNIVERSIDAD EAFIT

## Example



Figure 4 : Interval-valued polynomial graphic.

## Parameter Estimation

## UNIVERSIDAD EAFIT

## What do we look for?

## In a nutshell

Find a parameter configuration that reduces at most as possible the discrepancies between the observed data and the information provided by the model proposed.
$\min \sum_{i=1}^{m}\left[m\left(y_{i}\right)-m\left(\widehat{y}_{i}\right)\right]^{2}$
$\ell_{2}$ Norm - Least Squares

$$
\min \sum_{i=1}^{m} d_{H}\left(y_{i}, \widehat{y}_{i}\right)
$$

$\ell_{1}$ Norm - Least Absolute Values

## UNIVERSIDAD EAFIT

## $\ell_{2}$ Norm - Least Squares Estimation



Figure 5: Parameter estimation result using OLS.

## Parameter Estimation

## UNIVERSIDAD <br> EAFIT

## $\ell_{1}$ Norm - Heuristic



Figure 6: Parameter estimation result using Differential Evolution.

## Parameter Estimation

## UNIVERSIDAD EAFIT

## $\ell_{1}$ Norm - CVX



Figure 7: Parameter estimation result using CVX .

## Next Challenges

## Experimental Application

$$
\frac{\partial^{2} u}{\partial t^{2}}=c^{2} \nabla^{2} u t
$$

What is required?

- Experimental Data
- Numerical Methods - Computational Implementation
- Estimates Validation


## References (I)

1 R. Moore, R. Kearfott and M. Cloud, Introduction to interval analysis. Philadelphia, PA: Society for Industrial and Applied Mathematics, 2009.

2 H. Wu, 'The Karush-Kuhn-Tucker optimality conditions in an optimization problem with interval-valued objective function', European Journal of Operational Research, vol. 176, no. 1, pp. 46-59, 2007.

3 A. Tarantola, Inverse problem theory and methods for model parameter estimation. Philadelphia, PA: Society for Industrial and Applied Mathematics, 2005.

## References (II)

4 Michael Grant and Stephen Boyd. Graph implementations for nonsmooth convex programs, Recent Advances in Learning and Control (a tribute to M. Vidyasagar), V. Blondel, S. Boyd, and H. Kimura, editors, pages 95-110, Lecture Notes in Control and Information Sciences, Springer, 2008. http://stanford.edu/~boyd/graph_dcp.html.

5 Michael Grant and Stephen Boyd. CVX: Matlab software for disciplined convex programming, version 2.0 beta. http://cvxr.com/cvx, September 2013.

## Examples

## UNIVERSIDAD EAFIT

## Addition - Example

## Addition

$$
X=[1,2] \quad Y=[-4,5]
$$

$$
X+Y=[1,2]+[-4,5]=[1+(-4), 2+5]=[-3,7]
$$

## Examples

## UNIVERSIDAD EAFIT

## Negative - Example

Negative

$$
\begin{gathered}
X=[-5,2] \\
-X=[-2,-(-5)]=[-2,5]
\end{gathered}
$$

## Examples

## UNIVERSIDAD EAFIT

## Substraction - Example

## Substraction

$$
\begin{gathered}
X=[-5,2] \quad Y=[-1,9] \\
X+(-Y)=[-5,2]+[-9,1]=[-14,3]
\end{gathered}
$$

## Examples

## UNIVERSIDAD <br> EAFIT.

## Scalar Multiplication - Example

## Scalar Multiplication (I)

$$
\begin{gathered}
X=[-5,2] \quad k=3 \\
3 X=[-5 \cdot 3,2 \cdot 3]=[-15,6]
\end{gathered}
$$

## Scalar Multiplication (II)

$$
\begin{gathered}
X=[-5,2] \quad k=-8 \\
-8 X=[2 \cdot-8,-5 \cdot-8]=[-16,40]
\end{gathered}
$$

## Examples

## UNIVERSIDAD <br> EAFIT

## Product - Example

## Product

$$
\begin{gathered}
X=[-5,2] \quad Y=[-1,9] \\
S=\{(-5)(-1),(-5)(9),(2)(-1),(2)(9)\} \\
X Y=[\min S, \max S]=[-45,18]
\end{gathered}
$$

## Examples

## UNIVERSIPAD

## Multiplicative Inverse - Example

Multiplicative Inverse (I)

$$
X=[2,8] \rightarrow \frac{1}{X}=\left[\frac{1}{8}, \frac{1}{2}\right]
$$

Multiplicative Inverse (II)

$$
\begin{gathered}
X=[-1,5] \\
\frac{1}{X}=\left\{\frac{1}{x}: x \in X\right\}=(-\infty, \infty)
\end{gathered}
$$

## Examples

## UNIVERSIDAD <br> EAFIT

## Division - Example

## Division

$$
\begin{gathered}
X=[-5,2] \quad Y=[3,7] \\
\frac{1}{Y}=\left[\frac{1}{7}, \frac{1}{3}\right] \\
S=\left\{(-5)\left(\frac{1}{7}\right),(-5)\left(\frac{1}{3}\right),(2)\left(\frac{1}{7}\right),(2)\left(\frac{1}{3}\right)\right\} \\
\frac{X}{Y}=[\min S, \max S]=\left[-\frac{5}{3}, \frac{2}{3}\right]
\end{gathered}
$$

## Examples

## UNIVERSIDAD EAFIT

## Hukuhara Difference - Example

## Hukuhara Difference

$$
\begin{gathered}
X=[-5,2] \quad Y=[-1,3] \\
X \ominus Y=[-5,2] \ominus[-1,3]=[-5-(-1), 2-3] \\
X \ominus Y=[-4,-1]
\end{gathered}
$$

## Additive Inverses - Example

## Additive Inverses

$$
X=[-5,2]
$$

## Usual Difference

$$
\begin{gathered}
X-X=[-5,2]-[-5,2]=[-5,2]+[-2,5] \\
X-X=[-7,7]=7[-1,1] \ni[0,0]
\end{gathered}
$$

Hukuhara Difference

$$
X \ominus X=[-5,2] \ominus[-5,2]=[-5-(-5), 2-2]=[0,0]
$$

## UNIMERSIPAD

## Multiplicative Inverses - Example

## Multiplicative Inverses

$$
\begin{gathered}
X=[3,7] \\
\frac{1}{X}=\left[\frac{1}{7}, \frac{1}{3}\right] \\
S=\left\{(3)\left(\frac{1}{7}\right),(3)\left(\frac{1}{3}\right),(7)\left(\frac{1}{7}\right),(7)\left(\frac{1}{3}\right)\right\} \\
\frac{X}{X}=[\min S, \max S]=\left[\frac{3}{7}, \frac{7}{3}\right] \ni[1,1]
\end{gathered}
$$

